## 2024 年度若手研究者共同研究プロジェクト実施報告書

法政大学総長 殿

以下のとおり研究実施報告書を提出します。

	研究課題名:ビザンチン耐故障連合学習:ツリートポロジーの分散化と知識蒸留による アルゴリズム			
	研究代表者氏名:陳 錦華(CHEN JINHUA)			
基本	【在籍者】 研究科・専攻・学年:理工学研究科 応用情報工学専攻 博士後期課程 2年生 【修了者】 所属・職種:			
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	その他 研究分担者 : 趙 子涵(ZHAO Zihan)			
	研究期間: 2024年度 ~ 2026年度(※研究終了年度を記載)			
	※研究計画の進捗状況を中心に今年度の研究実施状況を記載してください。 From June 2024 to March 2025, the proposed research plan targeting the enhancement of fault tolerance, robust aggregation, and parameter privacy in Federated Learning (FL) systems has been effectively implemented. The plan was executed across three core aspects—theoretical research, experimental design, and data analysis—and yielded substantial results that align well with the original objectives.			
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The above work also introduced a TreeChainFL architecture. where blockchain and treestructured communication pathways enable tamper-resilient parameter exchange and verification. This contributes to system robustness against parameter pollution and Byzantine failures.

## 1.3 Privacy via Encryption during Training:

As shown in Fig.3, in "Dynamic Optimization of Vehicle Production Planning Using Federated Reinforcement Learning" (IEEE T-ITS), a CKKSbased homomorphic encryption scheme was implemented for protecting model parameters in collaborative reinforcement learning settings. This ensures privacy without compromising optimization performance



K Local Encrypted Model K Global Model 🕞 Local Training K Local Model 🖻 Parameters Encrypt 🔓 Parameters Decrypt

Fig. 3 Federated Reinforcement Learning with **Privacy-Preserving** for Vehicle **Production Planning** 

simulated using standard image classification datasets to evaluate defensive strategies.

In the transportation manufacturing domain, a novel federated reinforcement learning system was developed to optimize vehicle production planning. Two modules-DOPM (GRU-based) and HQPM (Transformer-based, as shown in Fig. 2)-were built to dynamically and efficiently schedule 1000 vehicles in less than 5 seconds, with over 95% fewer constraint violations compared to traditional methods.

The FL environments employed public datasets (e.g., CIFAR-10, CIFAR-100) and realworld vehicle production planning dataset, aligning with the initial plan. These were tested under both non-IID and Byzantine attack settings.

## 3. Comparative Data Analysis and Evaluation

The effectiveness of the proposed methods was quantitatively evaluated against multiple baselines: In the attack defense study, proposed methods outperformed FedAvg and Krum under poisoning conditions. In the scheduling task, HQPM under FL achieved 93.18% improvement in constraint satisfaction and 95.11% speed enhancement compared to NSGA-II. Evaluation metrics included accuracy, recall, reward values, and violation scores, thoroughly supporting the claims of robustness, scalability, and privacy-

	学会・論文・研究会等の別	タイトル	発行または発表年月	
	IEEE Transactions on Intelligent Transportation Systems	Dynamic Optimization of Vehicle Production Planning in Transportation Networks Using Federated Reinforcement Learning	January 2025	
	IEEE Consumer Electronics Magazine	Blockchain-Empowered Resilient Attack Defense in Federated Learning for Consumer Electronics	October 2024	
研	2024 IEEE 100th Vehicular Technology Conference (VTC2024-Fall)	A Byzantine-Fault-Tolerant Federated Learning Method Using Tree-Decentralized Network and Knowledge Distillation for Internet of Vehicles	November 2024	
究 業	2024 IEEE 99th Vehicular Technology Conference (VTC2024-Spring)	VeniclesEnhancingProductionPlanning in the Internet ofVehicles:A Transformer-basedFederatedReinforcementLearningApproach	September 2024	
績	2025IEEEConsumerCommunicationsandNetworkingConference(CCNC)Conference	EnhancingFederatedLearninginConsumerElectronicswithDecoupledKnowledgeDistillationagainstDataPoisoning	January 2025	
	その他(アピールすることがあ	かればご記入ください。)		