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受賞(研究)内容詳細	With an increasing need of contactless service after the outbreak of COVID-19 pandemic, a tele-operated robot started being deployed in a variety of service contexts. Interestingly, this emerging trend has opened opportunities for elderly and disabled people to participate in social activities through a tele-operated robot. Capturing this phenomenon, the objective of this study is, by taking an operator's perspective, to identify what aspects of a teleoperated robot can allow elderly and disabled people to participate in social activities and explore how these aspects can enhance their work engagement and performance. To address this, we propose a research model based on representation theory. The model will be examined by online survey targeting 40 disabled people who are currently working as staff via a tele-operated robot in the avatar robot café in Tokyo, Japan.